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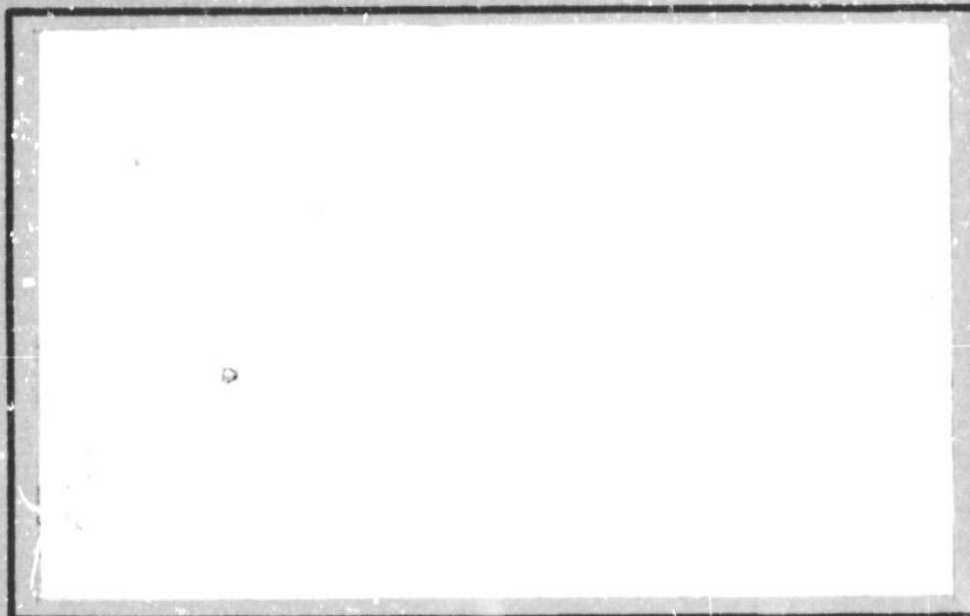
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(NASA-CR-175756) EXPERIMENTAL AND
ANALYTICAL INVESTIGATION OF FAN FLOW
INTERACTION WITH DOWNSTREAM STUTTS Interim
Report, 16 Jun. 1984 - 15 Mar. 1985
(Virginia Polytechnic Inst. and State Univ.)

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Interim Report on the Experimental and Analytical
Investigation of Fan Flow Interaction
with Downstream Struts

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Interim Report #1
for the period June 16, 1984 to March 15, 1985

Prepared for:

National Aeronautics and Space Administration
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This is an informal interim report recommended at this time for internal use only. The contents will be included in a formal report suitable for public release or distribution at a later time.

April 1985

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I. Introduction and Research Objectives

An important class of turbomachinery noise is produced by the interaction of the blades of a machine with flow perturbations within the machine. Such flow perturbations may be stationary in time and position, as would result from the potential field of a downstream strut. Disturbances originating from struts exist continually during operation of a machine, and will contribute to tone noise depending on the strength of the consequent flow response and pressure fluctuations.

The VPI&SU Turbomachinery Research Group had for some years carried on an investigation which was designed to provide insight into the fundamental aspects of fan rotor-downstream strut interaction (1,2,3). High response, miniature pressure transducers were embedded in the rotor blades of an experimental fan rig. Five downstream struts were placed at several downstream locations in the discharge flow annulus of the single-stage machine (Fig. 1). Significant interaction of the rotor blade surface pressures with the flow disturbance produced by the downstream struts was measured. Several numerical procedures for calculating the quasi-steady rotor response due to downstream flow obstructions were developed (3). A preliminary comparison of experimental and calculated fluctuating blade pressures on the rotor blades shows general agreement between the experimental and calculated values. Although progress has been made as a result of this effort, there are still areas in which further work is needed.

The objective of the program is to investigate the interaction of fan rotor flow with downstream struts. The results of this investigation will be an improved understanding of noise prediction with the goal of developing a design-for-noise capability and development of a data base for use in validating analytical prediction methods and noise-reduction concepts. The experimental program will focus on further data reduction of the existing data base from previous work.

The signal from the blade mounted pressure transducers will be used to calculate the unsteady lift and moment coefficients. In addition, power spectral analysis on the time-averaged data will be performed to retain the phase information. Both of these analyses will be used to validate the time-marching code, which was written to obtain the rotor blade flow response to a downstream strut row.

The present report gives a summary of the work for the period 6/16/84 - 3/15/85. Major topics to be covered in this report include the data transfer from NASA Langley Research Center to VPI&SU, further data reduction and the calculation of unsteady lift and moment. The report will conclude with a discussion of future plans.

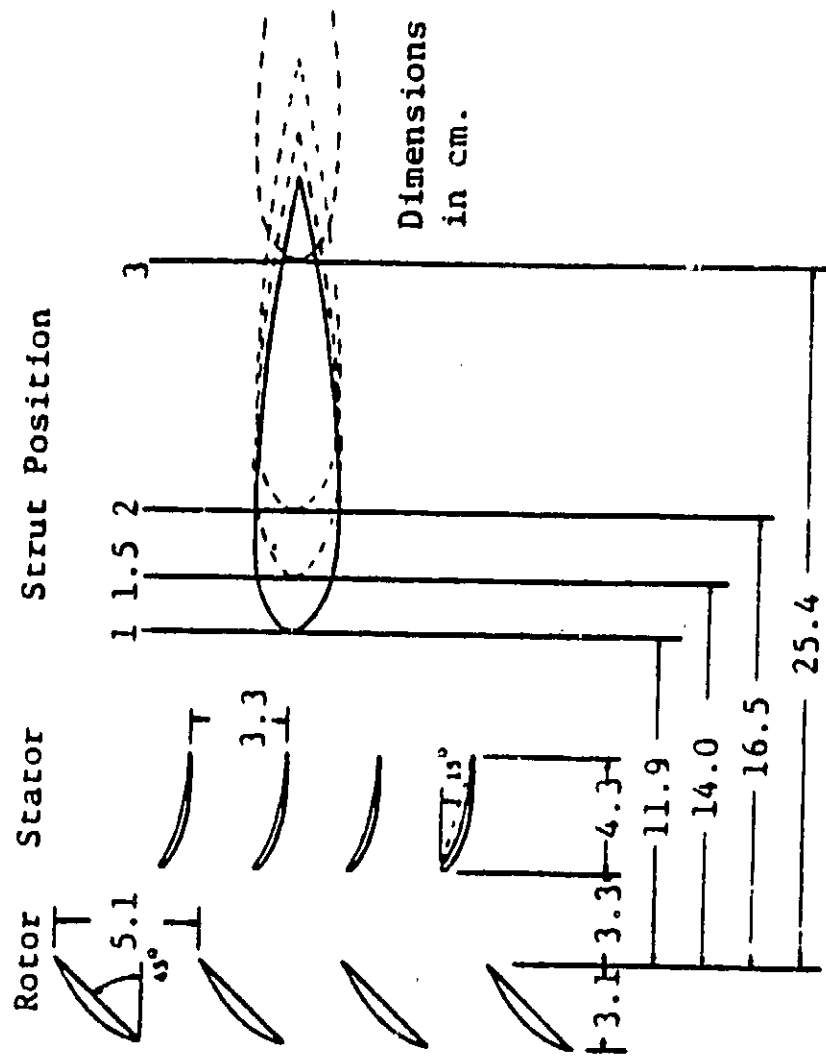


Fig. 1 Cross section of compressor showing rotor-stator-strut spacing

II. Data Transfer NASA Langley Research Center to VPI&SU

This section describes in detail the transfer of analog data recorded using FM tape recorder to digital data that can be reduced using computers at VPI&SU. A listing of the programs is provided in the Appendix.

1. Digitization of Analog Data

The original analog data were recorded on half-inch tape running at a speed of 15 inches per second (ips). The data were digitized in the Central Data Transcription Facility at NASA Langley Research Center, Analysis and Computation Division, Computer Management Branch, Data Management Section. The data were digitized with an anti-aliasing filter set at 5 kHz flat. The digitization gave 360 points per cycle of rotor revolution. Since the rotor rotational speed fluctuates with time, the corresponding data sample rate will have to be adjusted to account for this. The time increment between data point varies between 50 and 70 microseconds. The once per revolution signal is used to determine the sampling rate to give 360 points per rotation. The digitized data were written on magnetic tape using the UNIVAX VARIAN Model 77-600 computer. The specifications on the format of the data written on the magnetic tape include the following: Nine tracks; Non-labeled; Eddic; 1600 BPI; Fixed block binary; 16 Bit Integer Words and Two's compliment (Integer *2). The characteristics of the digitized data file on magnetic tape include the following: Blocksize 3840, Record length 3840 and Record format F.

2. Transfer of digitized data to computer at VPI&SU

The digitized data is transferred to an IBM 3081 system. The system operates under the control of VM (Virtual Machine) and OS/VS 2.3 (MVS) and has twenty-four (24) megabytes of memory. A series of software programs were developed to facilitate the data transfer. Figure 2 shows the flow chart to read the data off the magnetic tape. The first program, TPP CNTL, executes a system program (TPPRINT) which checks the tape characteristics. The program TPPRINT scans a tape and tells the number of files, the block storage size, and the number of records per block (thus record length). Record length is equal to blocksize/(number of records per block). TPPRINT also gives a machine language translation of the stored data, which is not readily readable.

Next step in the data transfer is to copy NASA's tape to a VPI system tape. The VPI system tape is permanently active, easier to access and is in readable format. Program TAPE TAPE is written to create the system tape.

Two programs were written to read from the system tape. TAPE LISTE shows the first 20 elements of every line. This is not a necessary operation, but allows a visual look at a swath of the whole file from top to bottom. The second program, TAPE LISTL, shows the first few lines of the file in totality. This allows viewing the arrangement of data on each line. Some prior knowledge of the data expected aids in selecting the format used in TAPE LISTL. (See appendix for a sample output from the program TAPE LISTL).

As mentioned earlier, the time increment between data point varies between 50 and 70 microseconds. The rotor test speed of 2900 RPM fluctuates

tuates. The analog data were digitized by 1) assigning a square wave pulse to match the once-per-rev signal, 2) dividing each pulse into 360 units, and 3) making a digital reading of each channel at each of 360 cycle positions in every revolution. Thus $\Delta \text{Time} \equiv \Delta \text{Position} / \text{rotor speed}$. Since the rotor speed fluctuates, the time increment fluctuates and thus cannot correlate exactly with position. It is decided that the data will be analyzed in the position domain.

Next, the square wave must be checked to see that 360 readings occur in each cycle. The file POS CHECK searches for the drop in each square wave (6000^+ followed by 600^+) and counts the number of entries since the preceeding square wave. It then shows the number of cycle positions in each revolutions, some truncation may occur and some cycles show 359 or 361 positions instead of 360. The approach taken here is to discard the bad cycles and the program CYCLE SELECT is written to do that. The program also ignores the first incomplete cycle and provides a printout of data points retained. A similar file, VOLT PLOT, performs the same data manipulation and then plots each channel, the square wave, and the once-per-rev signal versus cycle position for three good cycles.

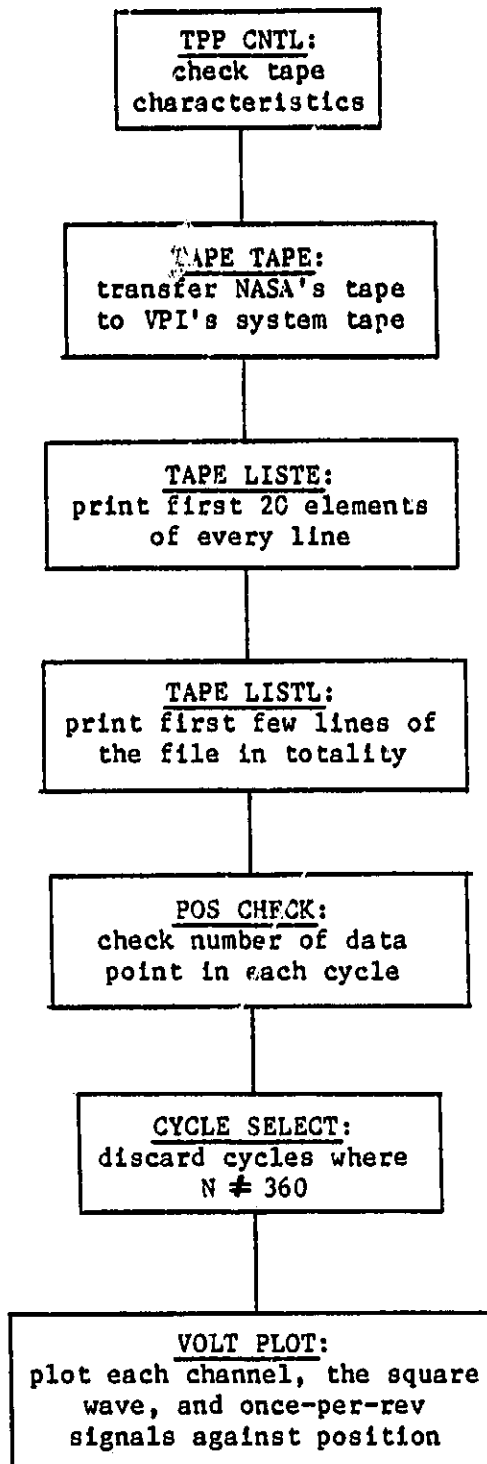


Fig. 2 Block diagram showing programs used in data transfer

III. Other Accomplishments

A. Presentation and Publication

"Calculation of Unsteady Fan Rotor Response Caused by Downstream Flow Distortions," by O'Brien, W. F., Jr., Richardson, S. M., and Ng, W. F., AIAA Paper No. 84-2282, presented by W. F. Ng at the AIAA 9th Aeroacoustics Conference, Williamsburg, Virginia, October 15-17, 1984, submitted for publication to AIAA Journal of Propulsion and Power.

B. Improvement in Analytical Code

Refinement in the time-marching code has led to improvement in the convergence of the solution. The calculation was carried out to 800 cycles with error in mass conservation less than 0.7% and error in total pressure conservation within 0.2%. The predicted pressure fluctuations on the blade surfaces compared very well with the measured data [4]. In addition, the Douglas-Newman program and the time-marching code are now better documented and readily available for future use.

C. Data Reduction

All analog data recorded on tapes had been digitized and transferred to the computers at VPI&SU for further data reduction. A computer program was written to take ensemble average on the data. Figure 3 shows some typical raw data and 200 cycles ensemble averaged data from pressure transducers mounted on the pressure and suction sides of the blade, with and without the downstream struts. The rotor is running at 2900 RPM and 15% surge margin. The transducers are at 50% span.

A program is also developed to calculate the unsteady lift and moment from the blade mounted transducers. The lift is calculated using

$$L = \sum_{i=1}^6 (P_p - P_s)_i \Delta A_i \quad (1)$$

where P_p and P_s are the pressures on the pressure and suction surfaces of the blade, ΔA is the differential area covered by each transducer. the pressures can be written as two components:

$$P_p(t) = \overline{P_p} + P'_p(t)$$

and

$$P_s(t) = \overline{P_s} + P'_s(t)$$

where \overline{P} is the steady-state pressure and P' is the time-varying pressure. Thus

$$L = \sum_{i=1}^6 (\overline{P_p} - \overline{P_s})_i \Delta A_i + \sum_{i=1}^6 (P'_p - P'_s)_i \Delta A_i \quad (2)$$

The first term is a constant and does not change with time. The second term can be calculated from the measurement using the blade mounted transducers. Figure 4.A shows the unsteady lift against rotor position for different downstream strut locations.

Similarly the unsteady moment is given by

$$M = \sum_{i=1}^6 d_i (\bar{P}_p - \bar{P}_s) \Delta A_i + \sum_{i=1}^6 d_i (P'_p - P'_s) \Delta A_i \quad (3)$$

where d_i is the distance between the transducer and quarter chord from the leading edge of the blade.

Again the first term does not change with time and the second term can be calculated from the blade mounted transducers. Figure 4-B shows the unsteady moment plotted against rotor position for different downstream strut locations.

D. Interactions with Industry

There is strong interest on the current work from the Aircraft Engine Business Group of General Electric Company at Cincinnati, Ohio. Discussions with their aeroacoustic design group have indicated that the problem is still of definite interest to them and to the aircraft manufacturer. They may use the analytical code for future investigations. Two specific areas of interest are: (1) Optimum positioning of the stators between the rotors and the struts to minimize unsteady interaction, (2) Effect of nonuniform circumferential spacing of the support struts on the fan-strut interaction (5). There will be continuous interactions between the Turbomachinery Research Group and aircraft engine industry.

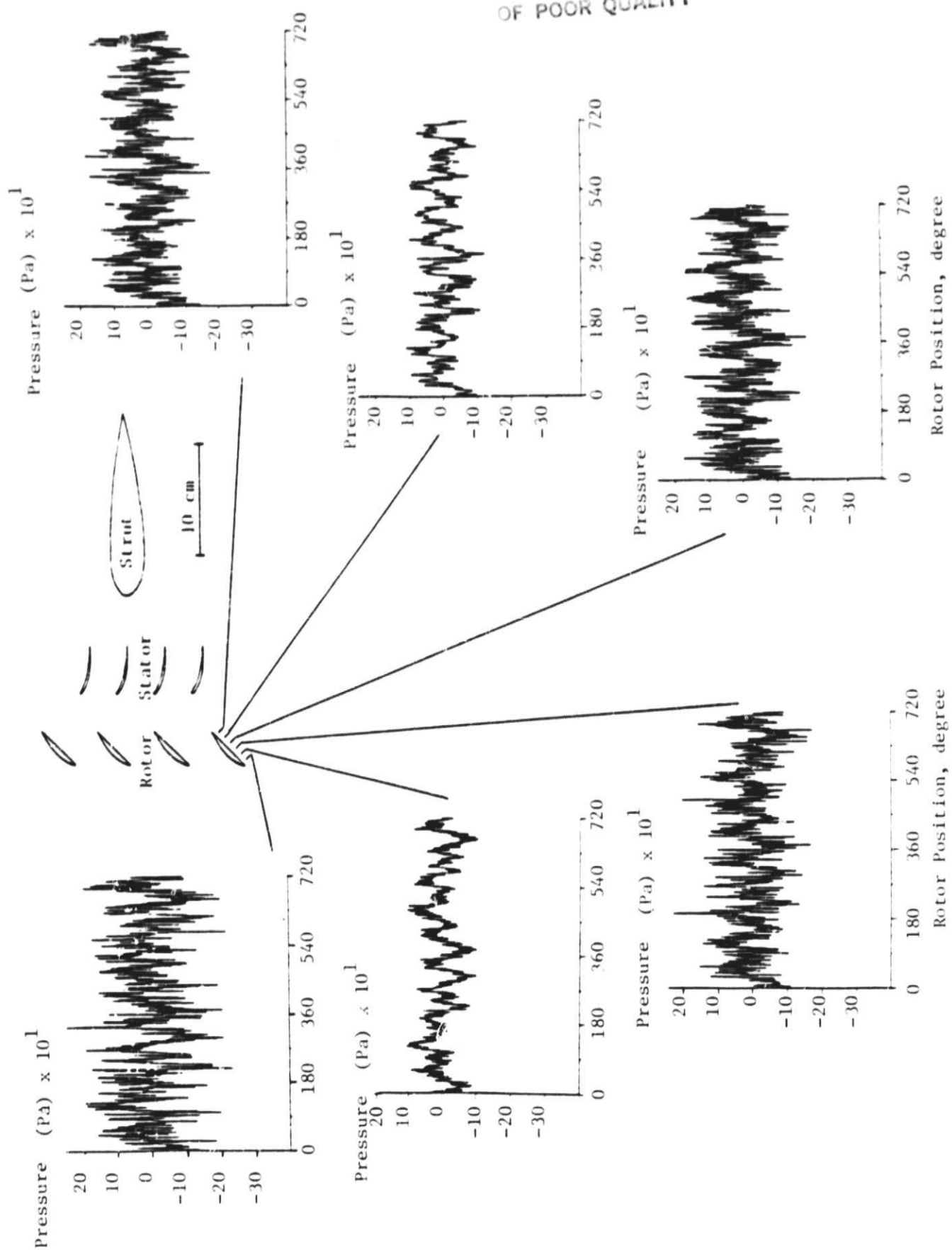


Fig. 3.A.1. Unsteady pressure on pressuresurface of rotor (raw data) with strut at 0.119 m from rotor trailing edge.

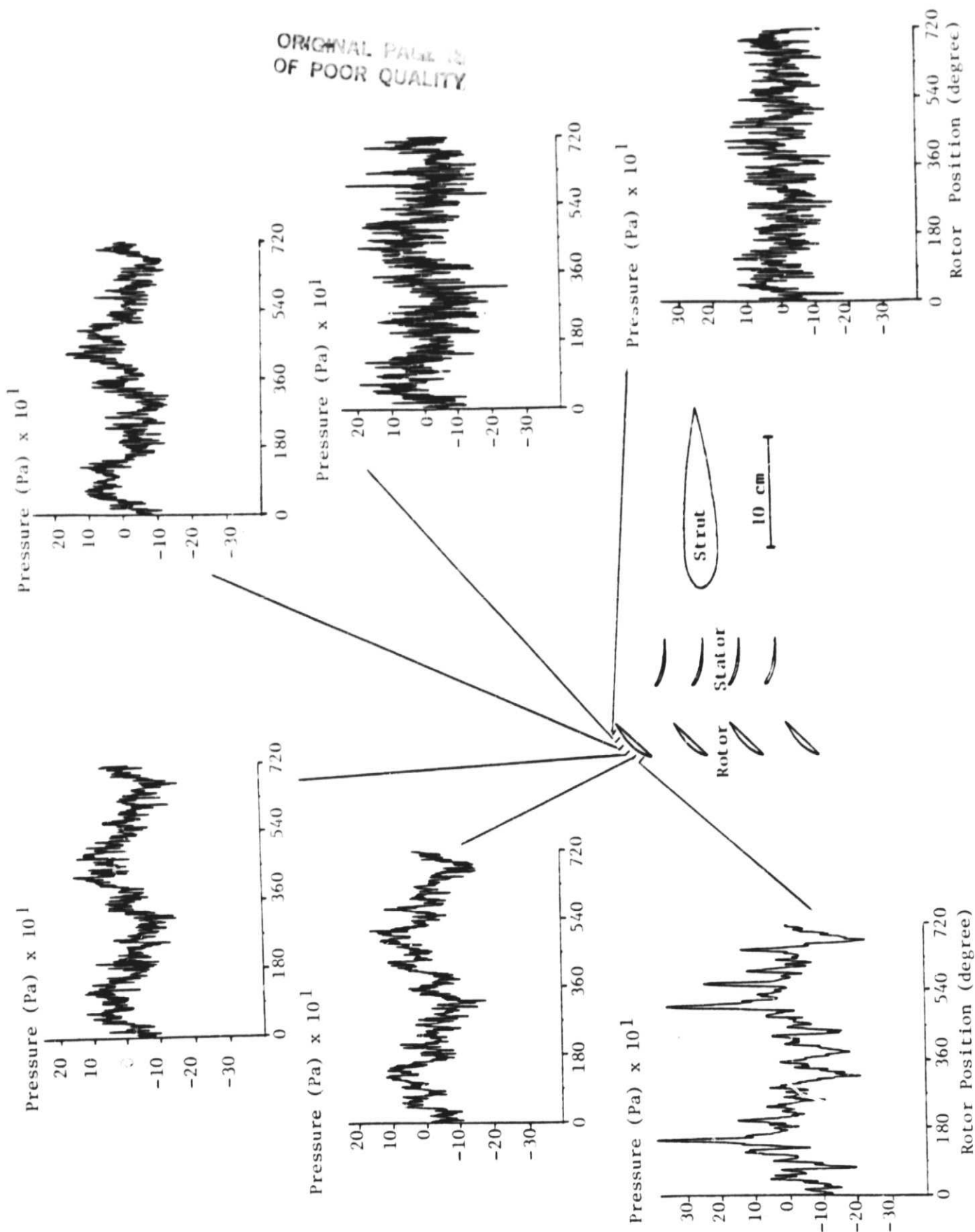


Fig. 3.A.2. Unsteady pressure on suction surface of rotor (raw data) with strut at 0.119 m from rotor trailing edge.

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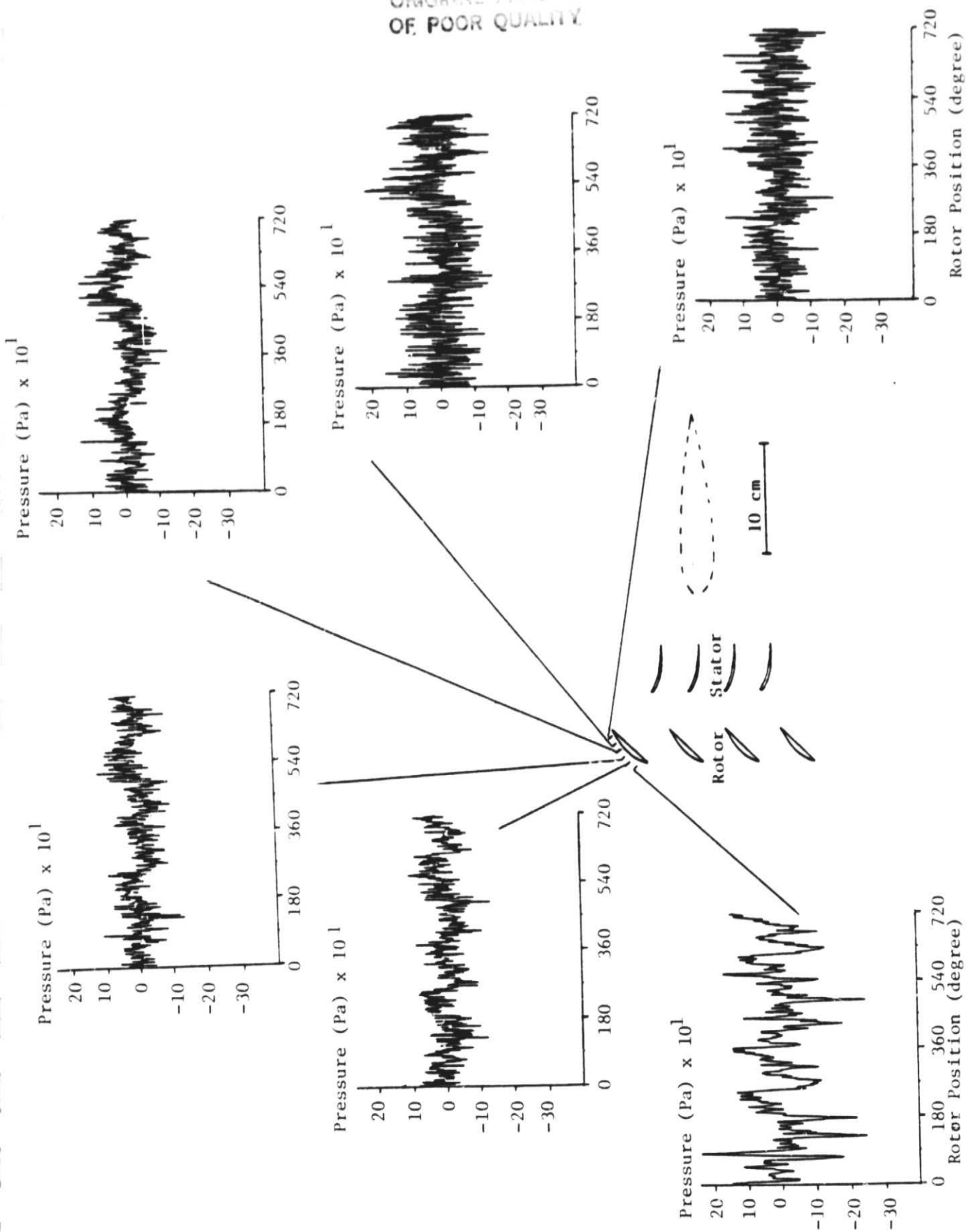


Fig. 3.B.2. Unsteady pressure on suction surface of rotor (raw data) with strut removed.

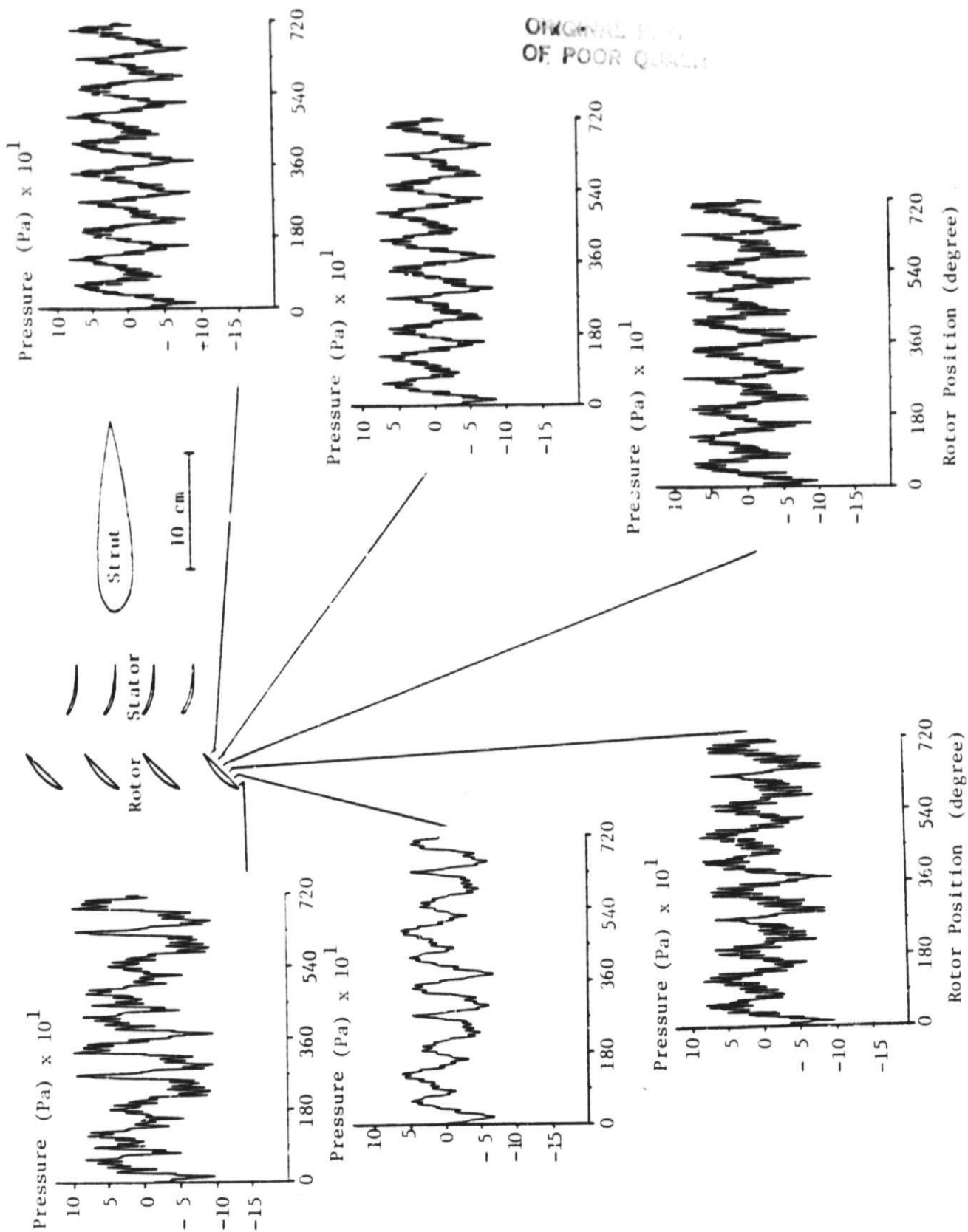


Fig. 3.C.1. Unsteady pressure on pressure surface of rotor (200 ensemble averaged) with strut at 0.119 m from rotor trailing edge.

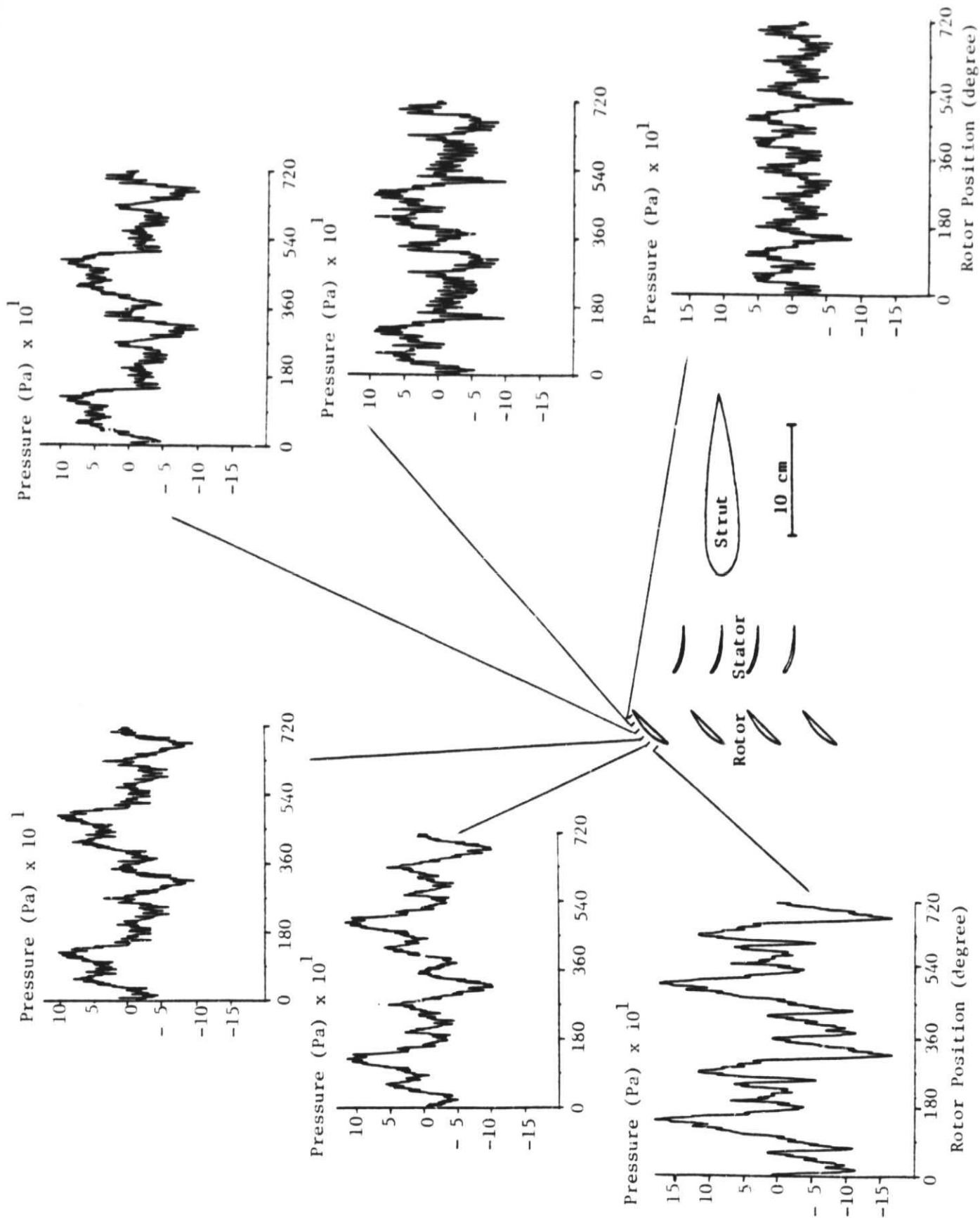


Fig. 3.C.2. Unsteady pressure on suction surface of rotor (200 ensemble averaged) with strut at 0.119 m from rotor trailing edge.

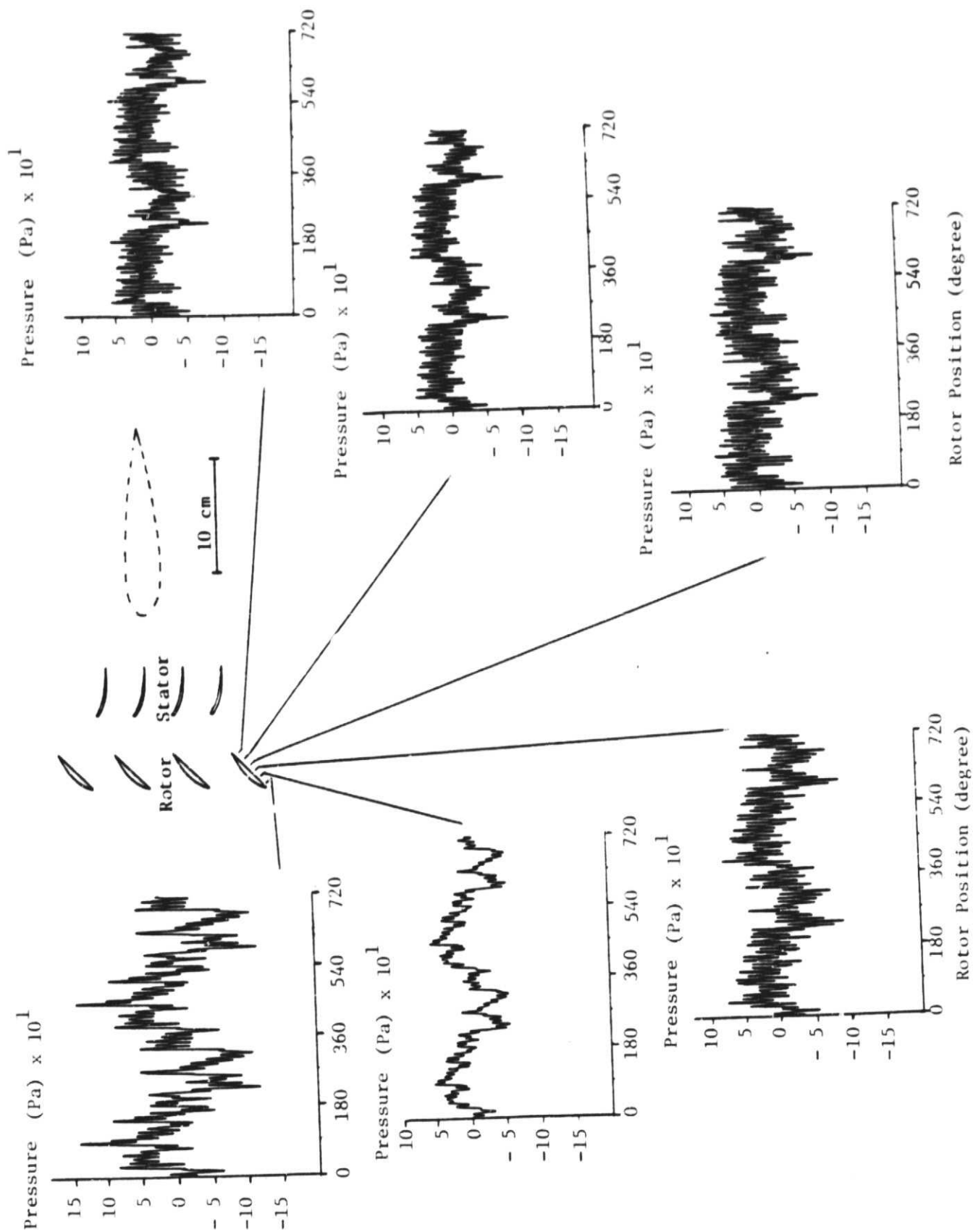


Fig. 3.D.1.1. Unsteady pressure on pressure surface of rotor (200 ensemble averaged) with strut removed.

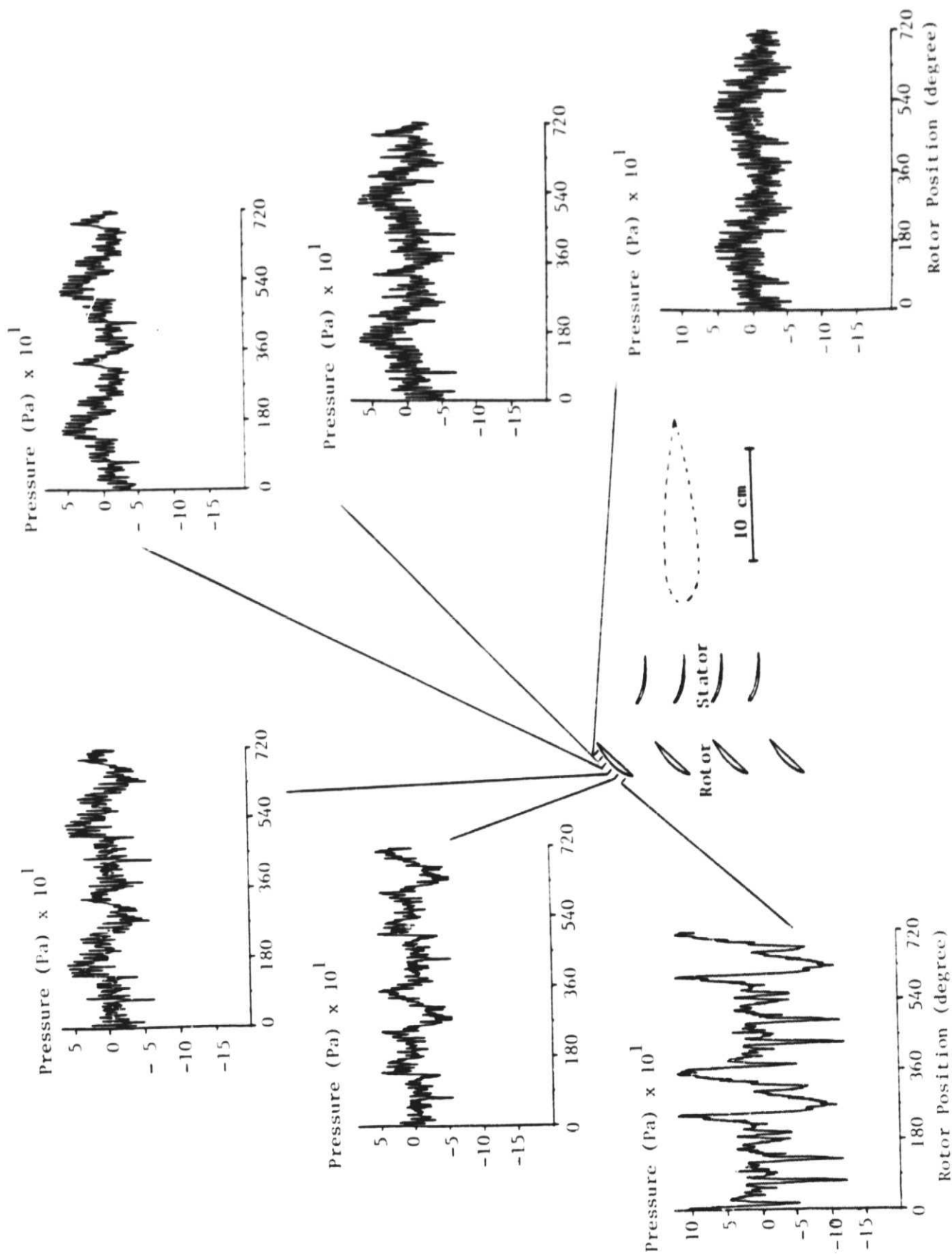


Fig. 3.D.2. Unsteady pressure on suction surface of rotor (200 ensemble averaged) with strut removed.

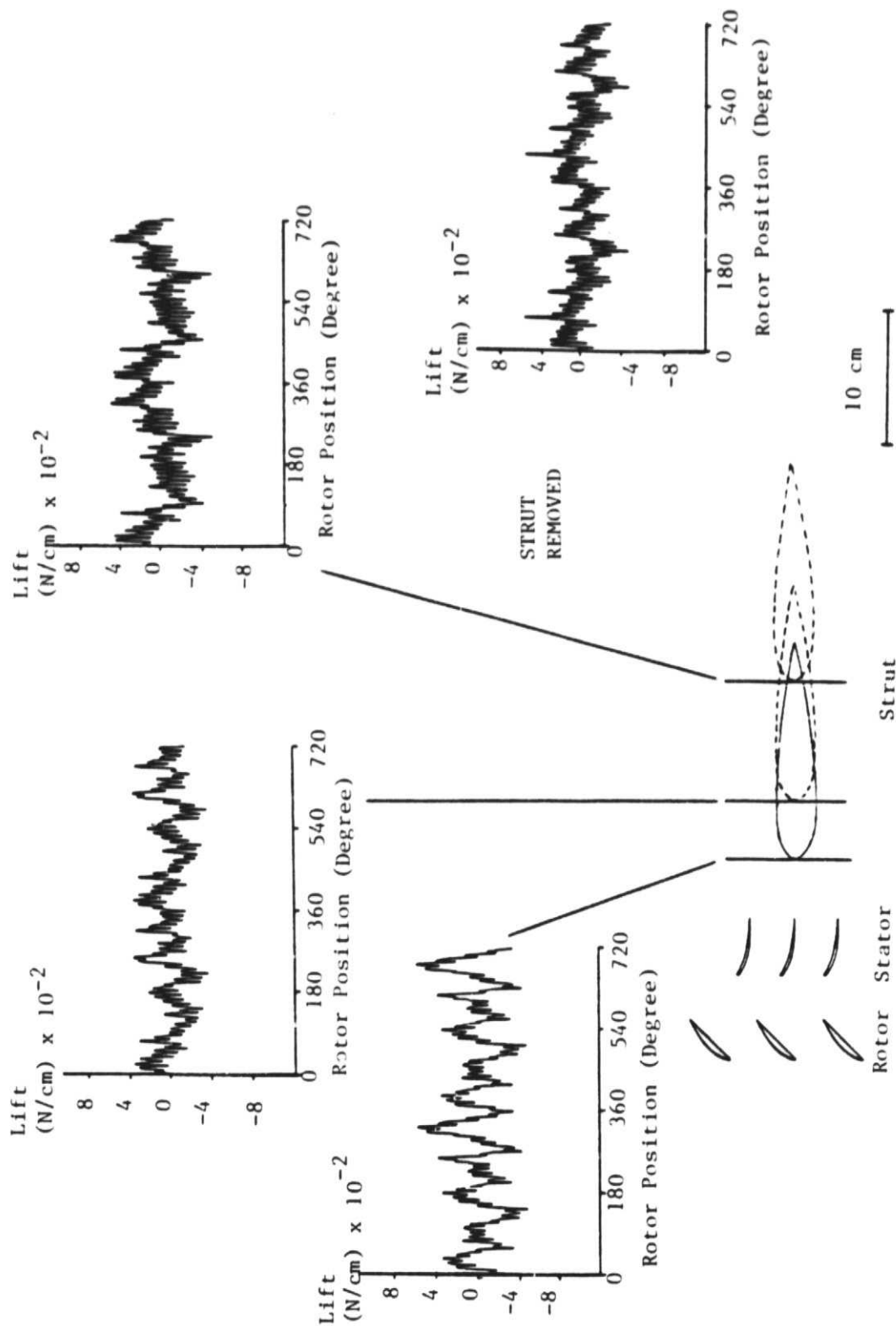


Fig. 4.A. Unsteady lift as a function of strut positions.

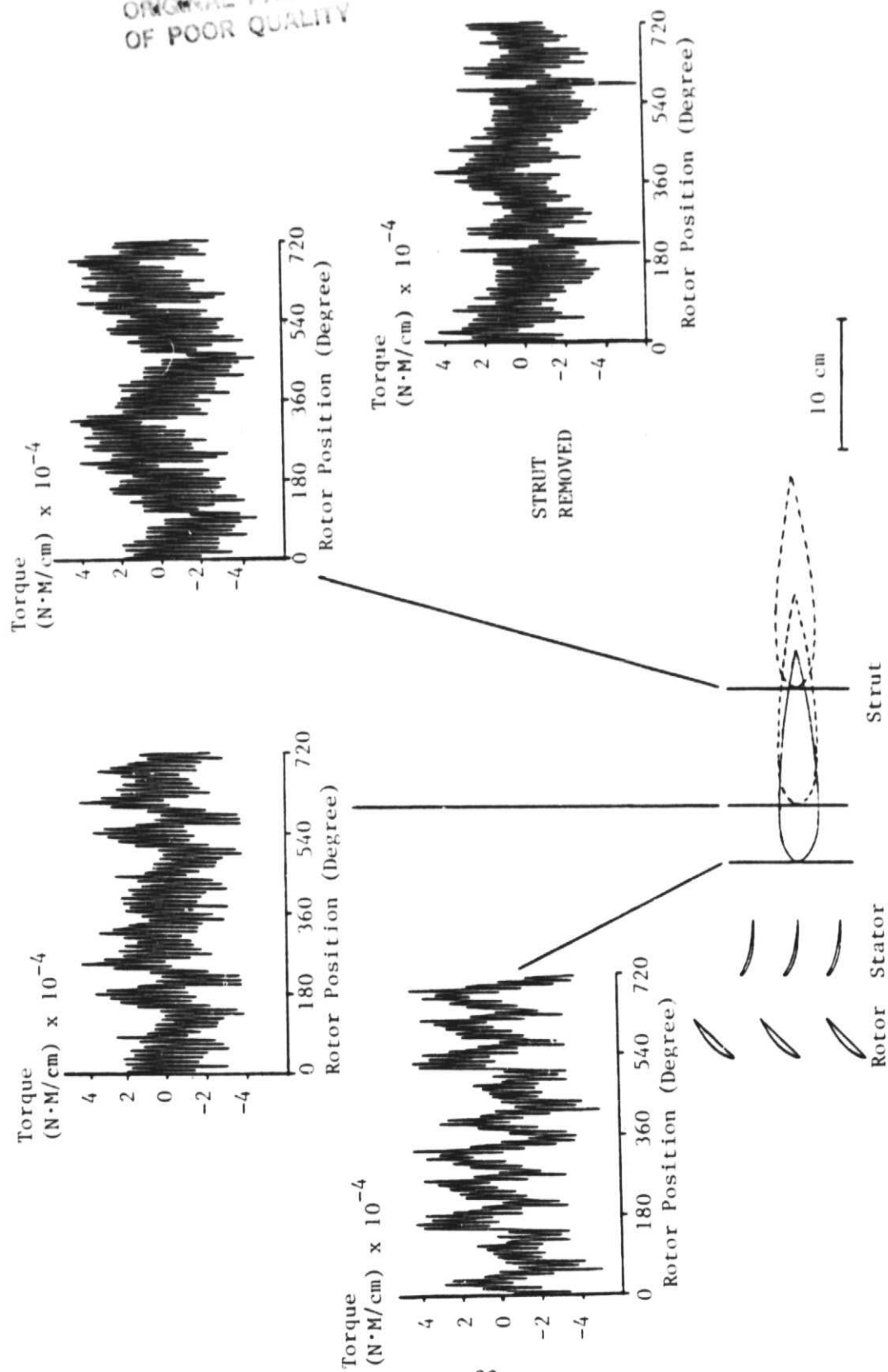


Fig. 4.B. Unsteady torque as a function of strut positions

IV. Summary and Future Plan

All analog data recorded on tapes have been digitized and successfully transferred to the computers at VPI&SU for further data reduction. In addition, a program was developed to calculate the unsteady lift and moment from the blade mounted transducers. The result of this analysis will be used to validate the numerical calculation. Work is in progress for implementing a digital Fast Fourier Transform (FFT) and Discrete Fourier Transform (DFT) subroutines for looking at spectral analysis of the data. A parametric study on the effect of different Fourier Transforms on the spectral analysis is underway.

In order to isolate the effect of downstream struts from other harmonic disturbances, it is necessary to subtract the amplitude of pressure fluctuation due to "background" disturbances from the amplitude of pressure fluctuation due to the downstream struts alone. In the previous data analysis, this was done by performing a power spectral analysis (FFT) on the raw data, then taking 200 averages of the power spectrum to give an overall spectral analysis. This was done for both cases; with and without the downstream struts. The difference in amplitude of the pressure fluctuation was then reported in Ref. (1). No phase information was retained in this data analysis.

Further data reduction will include an enhanced-signal spectral analysis (6) for the data set. The raw data will first be ensemble averaged (conditional averaging) and then a power spectral analysis will be performed on the averaged data while retaining the phase information. The vector difference in amplitude of the pressure fluctuation (with and without the downstream struts) can be obtained using a polar

plot (Nyquist plot). The result of this analysis will be compared to previous results as well as to the analytical model.

In addition, using the existing analytical code, an effort will be initiated to investigate the optimum positioning of the stators between the rotors and the struts to minimize unsteady interaction.

V. References

1. O'Brien, W. F., Jr., Reimers, S. L., and Richardson, S. M., "Interaction of Fan Rotor Flow with Downstream Struts," AIAA-83-0682, 1983.
2. Reimers, S. L., "An Investigation of Fan Flow Interaction with a Downstream Strut," M.S. Thesis, Department of Mechanical Engineering, VPI&SU, 1983.
3. Richardson, S. M., "Numerical Procedures for Calculating the Unsteady Rotor Response Caused by Downstream Flow Distortions," M.S. Thesis, Department of Mechanical Engineering, VPI&SU, 1983.
4. O'Brien, W. F., Jr., Richardson, S. M., and Ng, W. F., "Calculation of Unsteady Fan Rotor Response Caused by Downstream Flow Distortions," AIAA-84-2282, 1984, also submitted for publication to AIAA Journal of Propulsion and Power.
5. Gliebe, P. R. and Ho, P. Y., personal communications, June, October 1984.
6. Schoenster, James A., "Fluctuating Pressures on Fan Blades of a Turbofan Engine," NASA TP-1976, March 1982.

Appendix: Listing of programs used in data transfer

1. Program TPP CNTL - execute a system program (TPPRINT) which checks the tape characteristics.

TPP CNTL

```
//B0589TLO JOB 529E5,'TIM OLSEN',REGION=1024K,TIME=(,59)
//*JOBPARM LINES=99
//*PRIORITY STANDARD
//*LONGKEY WINGFAL
//STEP0001 EXEC PGM=TPPRINT          SYSTEM PROGRAM WHICH CHECKS TAPE
//SYSPRINT DD SYSOUT=*              CHARACTERISTICS.
//SYSUT1 DD DSN=VPI13,
//                                     DISP=OLD,
//                                     UNIT=TAPE,
//                                     LABEL=(1,NL),
//                                     VOL=SER=VPI13,
//                                     DCB=BLKSIZE=32000 LARGEST POSSIBLE; TAPE WILL PROBABLY
//SYUT2 DD SYSOUT=*                 HAVE SMALLER BLOCKSIZE. DSN AND VOL
//SYSIN DD *                         GIVE NAME OF NASA TAPE BEING CHECKED.
FILES=99,STOFAFT=3
//
//
```

2. Program TAPE TAPE - transfer NASA's tape to VPI's system tape.

TAPE TAPE

```
//B0589TLO JOB 529E5,'TIM OLSEN',REGION=1536K,TIME=(,59)
/*LONGKEY WINGFAL
/*ROUTE PRINT VPIVM1.OLSENTL
/*ROUTE PUNCH VPIVM1.OLSENTL
/*JOBPARM LINES=10
/*PRIORITY IDLE
//STEP0001 EXEC PLIXCLG
//PLI.SYSIN DD *
* PROCESS SOURCE, FLAG(I), GOSTMT ;
  READTP ;
    PROCEDURE OPTIONS( MAIN ) ;
    DECLARE SYSPRINT OUTPUT PRINT FILE ;
    DECLARE SYSIN INPUT RECORD FILE ;
    DECLARE OUTFIL OUTPUT RECORD FILE ;
    DECLARE DATA( 1920 ) FIXED BINARY( 15 ) ;
    DECLARE COUNT FIXED BINARY( 31 ) ;
    DECLARE END_OF_FILE FIXED BINARY( 31 ) INITIAL( 0 ) ;
    ON ENDFILE( SYSIN ) END_OF_FILE = 1 ;
    ON ERROR SNAP BEGIN ;
      ON ERROR SYSTEM ;
      PUT DATA ;
      STOP ;
    END ;
    DO WHILE( END_OF_FILE = 0 ) ;
      READ FILE( SYSIN ) INTO( DATA ) ;
      WRITE FILE( OUTFIL ) FROM( DATA ) ;
    END ;
  END READTP ;
/* VOL SHOWS OLD TAPE NAME; LABEL & DSN SHOW FILE'S POSITION ON TAPE.
//GO.SYSIN DD DSN=FILE1,
//          DISP=OLD,
//          UNIT=TAPE,
//          LABEL=(1,NL),
//          VOL=SER=VPI17,
//          DCB=(RECFM=F,LRECL=3840,BLKSIZE=3840)
/* SYSIN REFERS TO OLD NASA TAPE; OUTFIL REFERS TO NEW SYSTEM TAPE.
/* DSN SHOWS ASSIGNED FILE NAME ON NEW TAPE; LABEL SHOWS FILE'S
/* POSITION ON TAPE; SER='SERIAL #', ASSIGNED BY SYSTEM FIRST TIME
/* AND SHOWN IN OUTPUT, SUBSEQUENTLY GIVEN BY USER.
//GO.OUTFIL DD DSN=A529E5.VPI17.FILE1,
//          DISP=(NEW,PASS),
//          UNIT=TAPE,
//          LABEL=(19,SL,EXPDT=88304),
//          VOL=(,RETAIN,,,SER=200109),
//          DCB=(RECFM=VB,LRECL=3844,BLKSIZE=16000,DEN=4)
//GO.DD1 DD DSN=88G0SET,DISP=(OLD,DELETE)
/* THIS BLOCK MAY BE REPEATED FOR EACH FILE DESIRED WITH THE STEP #
/* CHANGED AND THE FILE ATTRIBUTES ADJUSTED.
//STEP0002 EXEC PLIXCLG
//PLI.SYSIN DD *
* PROCESS SOURCE, FLAG(I), GOSTMT ;
  READTP ;
    PROCEDURE OPTIONS( MAIN ) ;
    DECLARE SYSPRINT OUTPUT PRINT FILE ;
    DECLARE SYSIN INPUT RECORD FILE ;
```

Program TAPE TAPE continued

TAPE TAPE

```
DECLARE OUTFIL OUTPUT RECORD FILE ;
DECLARE DATA( 1920 ) FIXED BINARY( 15 ) ;
DECLARE COUNT FIXED BINARY( 31 ) ;
DECLARE END_OF_FILE FIXED BINARY( 31 ) INITIAL( 0 ) ;
ON ENDFILE( SYSIN ) END_OF_FILE = 1 ;
ON ERROR SNAP BEGIN ;
    ON ERROR SYSTEM ;
    PUT DATA ;
    STOP ;
END ;
DO WHILE( END_OF_FILE = 0 ) ;
    READ FILE( SYSIN ) INTO( DATA ) ;
    WRITE FILE( OUTFIL ) FROM( DATA ) ;
END ;
END READTP ;
/*
//GO.SYSIN DD DSN=FILE2,
//          DISP=OLD,
//          UNIT=TAPE,
//          LABEL=(2,NL),
//          VOL=SER=VPI17,
//          DCB=(RECFM=F,LRECL=3840,BLKSIZE=3840)
//GO.OUTFIL DD DSN=A529E5.VPI17.FILE2,
//            DISP=(NEW,PASS),
//            UNIT=TAPE,
//            LABEL=(20,SL,EXPDT=88304),
//            VOL=(,RETAIN,,,REF=*.STEP0001.GO.OUTFIL),
//            DCB=(RECFM=VB,LRECL=3844,BLKSIZE=16000,DEN=4)
//GO.DD1 DD DSN=88G0SET,DISP=(OLD,DELETE)
//STEP0003 EXEC PLIXCLG
//PLI.SYSIN DD *
* PROCESS SOURCE, FLAG(1), GOSTMT ;
READTP ;
    PROCEDURE OPTIONS( MAIN ) ;
    DECLARE SYSPRINT OUTPUT PRINT FILE ;
    DECLARE SYSIN INPUT RECORD FILE ;
    DECLARE OUTFIL OUTPUT RECORD FILE ;
    DECLARE DATA( 1920 ) FIXED BINARY( 15 ) ;
    DECLARE COUNT FIXED BINARY( 31 ) ;
    DECLARE END_OF_FILE FIXED BINARY( 31 ) INITIAL( 0 ) ;
    ON ENDFILE( SYSIN ) END_OF_FILE = 1 ;
    ON ERROR SNAP BEGIN ;
        ON ERROR SYSTEM ;
        PUT DATA ;
        STOP ;
    END ;
    DO WHILE( END_OF_FILE = 0 ) ;
        READ FILE( SYSIN ) INTO( DATA ) ;
        WRITE FILE( OUTFIL ) FROM( DATA ) ;
    END ;
END READTP ;
/*
//GO.SYSIN DD DSN=FILE3,
//          DISP=OLD,
//          UNIT=TAPE,
```

Program.TAPE TAPE continued

TAPE TAPE

```
//          LABEL=(3,NL),
//          VOL=SER=VPI17,
//          DCB=(RECFM=F,LRECL=3840,BLKSIZE=3840)
//GO.OUTFIL DD DSN=A529E5.VPI17.FILE3,
//          DISP=(NEW,PASS),
//          UNIT=TAPE,
//          LABEL=(21,SL,EXPDT=88304),
//          VOL=(,RETAIN,,,SER=200109),
//          DCB=(RECFM=VB,LRECL=3844,BLKSIZE=16000,DEN=4)
//GO.DD1 DD DSN=88GOSET,DISP=(OLD,DELETE)
//STEP0004 EXEC PLIXLG
//PLI.SYSIN DD *
* PROCESS SOURCE, FLAG(1), GOSTMT ;
  READTP ;
    PROCEDURE OPTIONS( MAIN ) ;
    DECLARE SYSPRINT OUTPUT PRINT FILE ;
    DECLARE SYSIN INPUT RECORD FILE ;
    DECLARE OUTFIL OUTPUT RECORD FILE ;
    DECLARE DATA( 1920 ) FIXED BINARY( 15 ) ;
    DECLARE COUNT FIXED BINARY( 31 ) ;
    DECLARE END_OF_FILE FIXED BINARY( 31 ) INITIAL( 0 ) ;
    ON ENDFILE( SYSIN ) END_OF_FILE = 1 ;
    ON ERROR SNAP BEGIN ;
      ON ERROR SYSTEM ;
      PUT DATA ;
      STOP ;
    END ;
    DO WHILE( END_OF_FILE = 0 ) ;
      READ FILE( SYSIN ) INTO( DATA ) ;
      WRITE FILE( OUTFIL ) FROM( DATA ) ;
    END ;
  END READTP ;
/*
//GO.SYSIN DD DSN=FILE4,
//          DISP=OLD,
//          UNIT=TAPE,
//          LABEL=(4,NL),
//          VOL=SER=VPI17,
//          DCB=(RECFM=F,LRECL=3840,BLKSIZE=3840)
//GO.OUTFIL DD DSN=A529E5.VPI17.FILE4,
//          DISP=(NEW,PASS),
//          UNIT=TAPE,
//          LABEL=(22,SL,EXPDT=88304),
//          VOL=(,RETAIN,,,REF=*.STEP0001.GO.OUTFIL),
//          DCB=(RECFM=VB,LRECL=3844,BLKSIZE=16000,DEN=4)
//GO.DD1 DD DSN=88GOSET,DISP=(OLD,DELETE)
//
```

3. Program TAPE LISTE - read from the system tape and print the first 20 elements of every line.

TAPE LISTE

```
//B0589TLO JOB 529E5,'TIM LSEN',REGION=1536K,TIME=(,59)
/*JOBPARM LINES=40
/*PRIORITY IDLE
//STEP0001 EXEC FORTVCG
//FORT.SYSIN DD *
    INTEGER*2 DATA( 1920 )
10 CONTINUE
    READ( 5, END = 20 ) DATA
    WRITE( 6, 99 ) ( DATA( I ), I = 1, 20 )
99    FORMAT( ' ', 20I6 )
    GOTO 10
20 CONTINUE
    STOP
    END
/* DSN SHOWS NAME AND LABEL SHOWS POSITION OF FILE DESIRED.
//GO.FT05F001 DD DSN=A529E5.VPI12.FILE1,
//    DISP=OLD,
//    UNIT=TAPE,
//    LABEL=(7,SL),
//    VOL=(,RETAIN,,,SER=200109) SERIAL # OF SYSTEM TAPE.
//
```


Program TAPE LISTE continued -

output

File #	Counter	Day	Hour	Min.	Second	Once per Sq. rev Wave	Channels	Channels	Channels
1	1913	207	1059	↓	596	55	604	5994	7640
1	1913	207	1059	↓	597	-24	613	5997	8620
1	1913	207	1059	↓	598	55	622	5998	9600
1	1913	207	1100	↓	0	-122	606	0	9600
1	1913	207	1100	↓	1	-56	622	1	1568
1	1913	207	1100	↓	2	1481	622	2	2530
1	1913	207	1100	↓	3	-94	622	3	3510
1	1913	207	1100	↓	4	-12871	640	4	4490
1	1913	207	1100	↓	5	-103	613	5	5478
1	1913	207	1100	↓	6	-420	613	6	6458
1	1913	207	1100	↓	7	-183	595	7	7438
1	1913	207	1100	↓	8	-103	622	8	8416
1	1913	207	1100	↓	9	-28	622	9	9390
1	1913	207	1100	↓	10	-47	613	10	1360
1	1913	207	1100	↓	11	-103	622	11	2330
1	1913	207	1100	↓	12	-36	622	12	3310
1	1913	207	1100	↓	13	-18	622	13	4280
1	1913	207	1100	↓	14	46	622	14	5260
1	1913	207	1100	↓	15	-56	622	15	6240
1	1913	207	1100	↓	16	9365	601	16	7220
1	1913	207	1100	↓	17	-3706	631	17	8200
1	1913	207	1100	↓	18	-112	631	18	9180
1	1913	207	1100	↓	19	-30	622	19	10115
1	1913	207	1100	↓	20	-46	604	20	11010
1	1913	207	1100	↓	21	-38	604	21	12010
1	1913	207	1100	↓	22	-112	622	22	13010
1	1913	207	1100	↓	23	-38	604	23	14010
1	1913	207	1100	↓	24	-112	622	24	15010
1	1913	207	1100	↓	25	-38	604	25	16010
1	1913	207	1100	↓	26	-112	622	26	17010
1	1913	207	1100	↓	27	-38	604	27	18010
1	1913	207	1100	↓	28	-112	622	28	19010
1	1913	207	1100	↓	29	-38	604	29	20010
1	1913	207	1100	↓	30	-112	622	30	21010
1	1913	207	1100	↓	31	-38	604	31	22010
1	1913	207	1100	↓	32	-112	622	32	23010
1	1913	207	1100	↓	33	-38	604	33	24010
1	1913	207	1100	↓	34	-112	622	34	25010
1	1913	207	1100	↓	35	-38	604	35	26010
1	1913	207	1100	↓	36	-112	622	36	27010
1	1913	207	1100	↓	37	-38	604	37	28010
1	1913	207	1100	↓	38	-112	622	38	29010
1	1913	207	1100	↓	39	-38	604	39	30010
1	1913	207	1100	↓	40	-112	622	40	31010
1	1913	207	1100	↓	41	-38	604	41	32010
1	1913	207	1100	↓	42	-112	622	42	33010
1	1913	207	1100	↓	43	-38	604	43	34010
1	1913	207	1100	↓	44	-112	622	44	35010
1	1913	207	1100	↓	45	-38	604	45	36010
1	1913	207	1100	↓	46	-112	622	46	37010
1	1913	207	1100	↓	47	-38	604	47	38010
1	1913	207	1100	↓	48	-112	622	48	39010
1	1913	207	1100	↓	49	-38	604	49	40010
1	1913	207	1100	↓	50	-112	622	50	41010
1	1913	207	1100	↓	51	-38	604	51	42010
1	1913	207	1100	↓	52	-112	622	52	43010
1	1913	207	1100	↓	53	-38	604	53	44010
1	1913	207	1100	↓	54	-112	622	54	45010
1	1913	207	1100	↓	55	-38	604	55	46010
1	1913	207	1100	↓	56	-112	622	56	47010
1	1913	207	1100	↓	57	-38	604	57	48010
1	1913	207	1100	↓	58	-112	622	58	49010
1	1913	207	1100	↓	59	-38	604	59	50010
1	1913	207	1100	↓	60	-112	622	60	51010
1	1913	207	1100	↓	61	-38	604	61	52010
1	1913	207	1100	↓	62	-112	622	62	53010
1	1913	207	1100	↓	63	-38	604	63	54010
1	1913	207	1100	↓	64	-112	622	64	55010
1	1913	207	1100	↓	65	-38	604	65	56010
1	1913	207	1100	↓	66	-112	622	66	57010
1	1913	207	1100	↓	67	-38	604	67	58010
1	1913	207	1100	↓	68	-112	622	68	59010
1	1913	207	1100	↓	69	-38	604	69	60010
1	1913	207	1100	↓	70	-112	622	70	61010
1	1913	207	1100	↓	71	-38	604	71	62010
1	1913	207	1100	↓	72	-112	622	72	63010
1	1913	207	1100	↓	73	-38	604	73	64010
1	1913	207	1100	↓	74	-112	622	74	65010
1	1913	207	1100	↓	75	-38	604	75	66010
1	1913	207	1100	↓	76	-112	622	76	67010
1	1913	207	1100	↓	77	-38	604	77	68010
1	1913	207	1100	↓	78	-112	622	78	69010
1	1913	207	1100	↓	79	-38	604	79	70010
1	1913	207	1100	↓	80	-112	622	80	71010
1	1913	207	1100	↓	81	-38	604	81	72010
1	1913	207	1100	↓	82	-112	622	82	73010
1	1913	207	1100	↓	83	-38	604	83	74010
1	1913	207	1100	↓	84	-112	622	84	75010
1	1913	207	1100	↓	85	-38	604	85	76010
1	1913	207	1100	↓	86	-112	622	86	77010
1	1913	207	1100	↓	87	-38	604	87	78010
1	1913	207	1100	↓	88	-112	622	88	79010
1	1913	207	1100	↓	89	-38	604	89	80010
1	1913	207	1100	↓	90	-112	622	90	81010
1	1913	207	1100	↓	91	-38	604	91	82010
1	1913	207	1100	↓	92	-112	622	92	83010
1	1913	207	1100	↓	93	-38	604	93	84010
1	1913	207	1100	↓	94	-112	622	94	85010
1	1913	207	1100	↓	95	-38	604	95	86010
1	1913	207	1100	↓	96	-112	622	96	87010
1	1913	207	1100	↓	97	-38	604	97	88010
1	1913	207	1100	↓	98	-112	622	98	89010
1	1913	207	1100	↓	99	-38	604	99	90010
1	1913	207	1100	↓	100	-112	622	100	91010
1	1913	207	1100	↓	101	-38	604	101	92010
1	1913	207	1100	↓	102	-112	622	102	93010
1	1913	207	1100	↓	103	-38	604	103	94010
1	1913	207	1100	↓	104	-112	622	104	95010
1	1913	207	1100	↓	105	-38	604	105	96010
1	1913	207	1100	↓	106	-112	622	106	97010
1	1913	207	1100	↓	107	-38	604	107	98010
1	1913	207	1100	↓	108	-112	622	108	99010
1	1913	207	1100	↓	109	-38	604	109	100010
1	1913	207	1100	↓	110	-112	622	110	101010
1	1913	207	1100	↓	111	-38	604	111	102010
1	1913	207	1100	↓	112	-112	622	112	103010
1	1913	207	1100	↓	113	-38	604	113	104010
1	1913	207	1100	↓	114	-112	622	114	105010
1	1913	207	1100	↓	115	-38	604	115	106010
1	1913	207	1100	↓	116	-112	622	116	107010
1	1913	207	1100	↓	117	-38	604	117	108010
1	1913	207	1100	↓	118	-112	622	118	109010
1	1913	207	1100	↓	119	-38	604	119	110010
1	1913	207	1100	↓	120	-112	622	120	111010
1	1913	207	1100	↓	121	-38	604	121	112010
1	1913	207	1100	↓	122	-112	622	122	113010
1	1913	207	1100	↓	123	-38	604	123	114010
1	1913	207	1100	↓	124	-112	622	124	115010
1	1913	207	1100	↓	125	-38	604	125	116010
1	1913	207	1100	↓	126	-112	622	126	117010
1	1913	207	1100	↓	127	-38	604	127	118010
1	1913	207	1100	↓	128	-112	622	128	119010
1	1913	207	1100	↓	129	-38	604	129	120010
1	1913	207	1100	↓	130	-112	622	130	121010
1	1913	207	1100	↓	131	-38	604	131	122010
1	1913	207	1100	↓	132	-112	622	132	123010
1	1913	207	1100	↓	133	-38	604	133	124010
1	1913	207	1100	↓	134	-112	622	134	125010
1	1913	207	1100	↓	135	-38	604	135	126010
1	1913	207	1100	↓	136	-112	622	136	127010
1	1913	207	1100	↓	137	-38	604	137	128010
1	1913	207	1100	↓	138	-112	622	138	129010
1	1913	207	1100	↓	139	-38	604	139	130010
1	1913	207	1100	↓	140	-112	622	140	131010
1	1913	207	1100	↓	141	-38	604	141	132010

4. Program TAPE LISTL - read from the system tape and show the first few lines of the file in totality.

TAPE LISTL

```
//B0589TLO JOB 529E5,'TIM OLSEN',REGION=1536K,TIME=(,59)
/*JOBPARM LINES=40
/*PRIORITY IDLE
//STEP0001 EXEC FORTVCG
//FORT.SYSIN DD *
    INTEGER*2 DATA( 1920 )
    DO 10 I=1,3
        READ(5) DATA
        WRITE(6,99) DATA
    99  FORMAT(1H ,5I6/,191(10I6/),5I6)
    10 CONTINUE
    STOP
    END
/*
//GO.FT05F001 DD DSN=A529E5.VPI12.FILE1,
//          DISP=OLD,
//          UNIT=TAPE,
//          LABEL=(7,SL),
//          VOL=(,RETAIN,,,SER=200109)
//
```

Program TAPE LISTL continued -

output

	File#	Remaining line length	Dummy	Day	Minute				
	↓	↓	↓	↓	↓				
	1	1913	0	207	1059				
5996	7580	-5854	-859	-1225	-5070	-651-12975	55	604	
5996	7640	-6966	-471	-1309	-4248	-1032-11726	-19	622	
5996	7700	-6038	-277	-4158	-6483	-2249-13269	-28	622	
5996	7750	-8271	-1006	-3573	-6972	-1887-13159	-75	613	
5996	7810	-9016	-665	-2599	-5402	-1868-11781	0	613	
5996	7870	-6985	-545	-1754	-5015	-1738-11909	-56	622	
5996	7930	-5809	-120	-1485	-3990	-670-10255	-112	622	
5996	7990	-3235	-573	-1392	-5255	-19 -9787	-19	604	
5996	8050	-5266	-582	-19	-3131	381 -9539	27	622	
5996	8100	-6599	184	-1513	-3731	232 -9621	-28	622	
5996	8150	-5459	-139	-567	-5485	-38-11560	-66	622	
5996	8210	-6075	765	-1040	-4581	-558-11376	18	631	
5996	8260	-7003	793	-3016	-6344	-1422-10825	27	631	
5996	8340	-6259	-231	-2293	-6529	-1078-12167	46	640	
5996	8390	-5928	138	-864	-3223	-930-10320	93	622	
5996	8450	-5533	1116	1011	-2272	176 -9180	27	622	
5996	8500	-4779	599	1410	-3417	817-10173	18	622	
.
.
.
Time	Time	Channel	2	3	4	5	6	Once	Square
(in		1						per	wave
seconds)								Rev	
.
.
.
0	0	0	0	0	0	0	0	0	0

(5 zeroes indicate end of line)

One line of original data (1920 elements)

5. Program POS CHECK - check number of data points in each cycle.

POS CHECK

```
//B0589TLO JOB 529E5,'T1' 'LSEN',REGION=1536K,TIME=(,59)
//*LONGKEY WINGFAL
//*JOBPARM LINES=40,CARDS=100
//*PRIORITY STANDARD
//STEP0001 EXEC FORTVCG
//FORT.SYSIN DD *
C***
C*** POS CHECK READS SYSTEM TAPE, CHECKS POSITION VS SQ WAVE.
C*** I, J, K COUNTERS; TEST & ON FOR CONTROL, POS = ROTOR
C*** ANGULAR POSITION, OPR = ONCE PER REV, SQW = SQUARE WAVE
C***
      INTEGER*2 DATA( 1920 )
      INTEGER I, J, K, POS, ON, TEST
      REAL SQW(95500)

C***
C*** READ DATA FROM TAPE, ASSIGN SQUARE WAVE
C***
      DO 10 I=1,500
        READ( 5 ) DATA
        DO 20 J=1,191
          SQW((I-1)*191+J) = DATA(10*KJ+5)
        20 CONTINUE
      10 CONTINUE

C***
C*** HEADING
C***
      WRITE(6,98)
C 98 FORMAT(1H1,4(' POS SQWAVE'))
      98 FORMAT(1H1,' K POS SW(K) SW(K+1)')
C***
C*** CHECK SQUARE WAVE, ASSIGN ROTOR ANGULAR POSITIONS
C*** WRITE POSITIONS AND CHANNEL VALUES
C***
      POS = 0
      ON = 0
      TEST = 0
      DO 30 K=1,95500
        IF (TEST.EQ.1) THEN
          TEST = 0
          POS = 0
          ON = 1
        ENDIF
        IF (SQW(K).GE.6000) THEN
          IF (SQW(K+1).LE.1000) THEN
            TEST = 1
            WRITE(6,92) K, (POS+1), SQW(K), SQW(K+1)
          92 FORMAT(1H ,2I6, 2F7.0)
          ENDIF
        ENDIF
        IF (ON.EQ.1) THEN
          POS = POS+1
          WRITE(6,99) K, POS, TIME(K), CH1(K), CH2(K), CH3(K),
C      + CH4(K), CH5(K), CH6(K), OPR(K), SQW(K)
          ENDIF
C 99 FORMAT(1H ,2I5,F8.0,8F7.0)
      30 CONTINUE
      STOP
      END

/*
//GO.FT05F001 DD DSN=A529E5.VPI10.FILE1,
// DISP=OLD,
// UNIT=TAPE,
// LABEL=(1,SL),
// VOL=(,RETAIN,,,SER=200109)
//
```

6. Program CYCLE SELECT - discard cycles where the number of points is not equal to 360.

CYCLE SELECT

```
//B0589TLO JOB 529E5,'TIM OLSEN',REGION=1536K,TIME=(,59)
/*LONGKEY WINGFAL
/*JOBPARM LINES=40,CARDS=100
/*PRIORITY STANDARD
//STEP0001 EXEC FORTVCG
//FORT.SYSIN DD *
C***
C*** CYCLE SELECT READS SYSTEM TAPE, FINDS CYCLES WITH 360 UNITS.
C*** I, J, K, L, M COUNTERS; TEST & ON FOR CONTROL, POS = ROTOR
C*** ANGULAR POSITION, OPR = ONCE PER REV, SQW = SQUARE WAVE,
C*** CYCLE = CYCLE NUMBER (IF ACCEPTED)
C***
      INTEGER*2 DATA( 1920 )
      INTEGER I, J, K, L, M, MNEW, POS, CYCLE, N
      REAL APOS(1146), CH1(1146), CH2(1146), CH3(1146)
      REAL CH4(1146), CH5(1146), CH6(1146), OPR(1146), SQW(1146)

C***
C*** READ DATA FROM TAPE, ASSIGN CHANNELS
C***
      N = 720
      DO 10 I=1,6
        READ( 5 ) DATA
        DO 20 J=1,191
          CH1((I-1)*191+J) = DATA(10*J-2)
          CH2((I-1)*191+J) = DATA(10*J-1)
          CH3((I-1)*191+J) = DATA(10*J)
          CH4((I-1)*191+J) = DATA(10*J+1)
          CH5((I-1)*191+J) = DATA(10*J+2)
          CH6((I-1)*191+J) = DATA(10*J+3)
          OPR((I-1)*191+J) = DATA(10*J+4)
          SQW((I-1)*191+J) = DATA(10*J+5)
        20 CONTINUE
      10 CONTINUE
C***
C*** HEADING
C***
      WRITE(6,98)
      98 FORMAT('1CYCLE POS ORIG APOS CHAN1 CHAN2 CHAN3 ',
+           'CHAN4 CHAN5 CHAN6 1/REV SQWAVE')
C***
C*** CHECK SQUARE WAVE, ASSIGN ROTOR ANGULAR POSITIONS,
C*** CHECK CYCLE FOR 360 POSITIONS, WRITE VALUES
C***
      POS = 0
      CYCLE = 0
      DO 30 K=1,(N+360)
        POS = POS + 1
        IF (SQW(K).GE.6000) THEN
          IF (SQW(K+1).LE.1000) THEN
            IF (POS.EQ.360) THEN
              CYCLE = CYCLE + 1
              POS = 0
            DO 40 L=1,360
              M = K - 360 + L
              MNEW = (CYCLE-1)*360 + L
```

Program CYCLE SELECT continued

CYCLE SELECT

```

                                APOS(MNEW) = MNEW
                                CH1(MNEW) = CH1(M)
                                CH2(MNEW) = CH2(M)
                                CH3(MNEW) = CH3(M)
                                CH4(MNEW) = CH4(M)
                                CH5(MNEW) = CH5(M)
                                CH6(MNEW) = CH6(M)
                                OPR(MNEW) = OPR(M)
                                SQW(MNEW) = SQW(M)
                                WRITE(6,99) CYCLE, L, M, APOS(MNEW), CH1(MNEW),
+                                     CH2(MNEW), CH3(MNEW), CH4(MNEW), CH5(MNEW),
+                                     CH6(MNEW), OPR(MNEW), SQW(MNEW)
99                                FORMAT(1H ,I3,2I5,F6.0,7F7.0,F6.0)
40                                CONTINUE
                                ELSE
                                POS = 0
                                ENDIF
                                ENDIF
                                ENDIF
30 CONTINUE
  STOP
  END
/*
//GO.FT05F001 DD DSN=A529E5.VPI10.FILE1,
//              DISP=OLD,
//              UNIT=TAPE,
//              LABEL=(1,SL),
//              VOL=(,RETAIN,,,SER=200109)
//
```

7. Program VOLT PLOT - plot data from each channel (1-6), square wave, and once-per-rev signals against position

VOLT PLOT

```
//B0589TLO JOB 529E5,'TIM OLSEN',REGION=1536K,TIME=(,99)
//XLONGKEY WINGFAL
//XJOBPARM LINES=40,CARDS=100
//XPRIORITY STANDARD
//STEP0001 EXEC FORTVCGV
//FORT.SYSIN DD *
C***
C*** VOLT PLOT READS SYSTEM TAPE, PLOTS CYCLES WITH 360 UNITS.
C*** I, J, K, L, COUNTERS; N = TOTAL # OF CYCLES, POS = ROTOR
C*** ANGULAR POSITION, OPR = ONCE PER REV, SQW = SQUARE WAVE,
C*** M = ORIGINAL DATA COUNT, MNEW = DATA COUNT OF ACCEPTED CYCLES,
C*** CYCT = CYCLE COUNTER (IF ACCEPTED)
C***
      INTEGER*2 DATA( 1920 )
      INTEGER I, J, K, L, M, MNEW, POS, CYCT, N
      REAL APOS(1146), CH1(1146), CH2(1146), CH3(1146)
      REAL CH4(1146), CH5(1146), CH6(1146), OPR(1146), SQW(1146)
      N = 3
C***
C*** READ DATA FROM TAPE, ASSIGN CHANNELS
C***
      DO 10 I=1,(INT(360*(N+1)/191)+1)
        READ( 5 ) DATA
        DO 20 J=1,191
          CH1((I-1)*191+J) = DATA(10*J-2)
          CH2((I-1)*191+J) = DATA(10*J-1)
          CH3((I-1)*191+J) = DATA(10*J)
          CH4((I-1)*191+J) = DATA(10*J+1)
          CH5((I-1)*191+J) = DATA(10*J+2)
          CH6((I-1)*191+J) = DATA(10*J+3)
          OPR((I-1)*191+J) = DATA(10*J+4)
          SQW((I-1)*191+J) = DATA(10*J+5)
        20 CONTINUE
      10 CONTINUE
C***
C*** HEADING
C***
      C      WRITE(6,98)
      C 98 FORMAT('1CYCLE POS ORIG APOS CHAN1 CHAN2 CHAN3 ',
      C      + ' CHAN4 CHAN5 CHAN6 1/REV SQWAVE')
C***
C*** CHECK SQUARE WAVE, ASSIGN ROTOR ANGULAR POSITIONS,
C*** CHECK CYCLE FOR 360 POSITIONS, WRITE VALUES
C***
      POS = 0
      CYCT = 0
      DO 30 K=1,((N+1)*360)
        POS = POS + 1
        IF (SQW(K).GE.6000) THEN
          IF (SQW(K+1).LE.1000) THEN
            IF (POS.EQ.360) THEN
              CYCT = CYCT + 1
              POS = 0
              DO 40 L=1,360
                M = K - 360 + L
```

Program VOLT PLOT continued

VOLT PLOT

```

MNEW = (CYCT-1)*360 + L
APOS(MNEW) = MNEW
CH1(MNEW) = CH1(M)
CH2(MNEW) = CH2(M)
CH3(MNEW) = CH3(M)
CH4(MNEW) = CH4(M)
CH5(MNEW) = CH5(M)
CH6(MNEW) = CH6(M)
OPR(MNEW) = OPR(M)
SQW(MNEW) = SQW(M)
C      +
C      +
C      +
C      99
C      40      FORMAT(1H ,I3,2I5,F6.0,7F7.0,F6.0)
              CONTINUE
              ELSE
                POS = 0
              ENDIF
            ENDIF
          ENDIF
        30 CONTINUE
C***
C*** PLOT SQUARE WAVE
C***
      AXX = 4.0 * N
      XFIR = 0.0
      XINC = 90.0
      AYY = 7.0
      YFIR = 0.0
      YINC = 1000.0
      APOS(N+1) = 0.0
      APOS(N+2) = 90.0
      SQW(N+1) = 0.0
      SQW(N+2) = 1000.0
      ITYPE = 0
      ITEXT = 11
      CALL PLOTS(0,0,50)
      CALL PLOT(1.,1.,-3)
      CALL VPISYM(0.75,7.0,0.12,'SQUARE WAVE',0.,11)
      CALL AXIS(0.0,0.0,'POSITION',-8,AXX,0.0,XFIR,XINC)
      CALL AXIS(0.0,0.0,'VOLTAGE',7,AYY,90.0,YFIR,YINC)
      CALL LINE(APOS,SQW,N,1,ITYPE,ITEXT)
      CALL PLOT(6.,6.,-999)
C***
C*** PLOT ONCE PER REV
C***
      AXX = 4.0 * N
      XFIR = 0.0
      XINC = 90.0
      AYY = 6.0
      YFIR = -15000.0
      YINC = 5000.0
      APOS(N+1) = 0.0
      APOS(N+2) = 90.0
      OPR(N+1) = -15000.0

```


Program VOLT PLOT continued

VOLT PLOT

```
OPR(N+2) = 5000.0
ITYPE = 0
ITEXT = 11
CALL PLOTS(0,0,50)
CALL PLOT(1.,1.,-3)
CALL VPISYM(0.75,6.0,0.12,'ONCE PER REV',0.,12)
CALL AXIS(0.0,0.0,'POSITION',-8,AXX,0.0,XFIR,XINC)
CALL AXIS(0.0,0.0,'VOLTAGE',7,AYY,90.0,YFIR,YINC)
CALL LINE(APOS,N,1,ITYPE,ITEXT)
CALL PLOT(6.,6.,-999)

C***
C*** PLOT CHANNEL 1
C***
AXX = 4.0 * N
XFIR = 0.0
XINC = 90.0
AYY = 4.0
YFIR = -16000.0
YINC = 4000.0
APOS(N+1) = 0.0
APOS(N+2) = 90.0
CH1(N+1) = -16000.0
CH1(N+2) = 4000.0
ITYPE = 0
ITEXT = 11
CALL PLOTS(0,0,50)
CALL PLOT(1.,1.,-3)
CALL VPISYM(0.75,6.0,0.12,'CHANNEL 1',0.,9)
CALL AXIS(0.0,0.0,'POSITION',-8,AXX,0.0,XFIR,XINC)
CALL AXIS(0.0,0.0,'VOLTAGE',7,AYY,90.0,YFIR,YINC)
CALL LINE(APOS,CH1,N,1,ITYPE,ITEXT)
CALL PLOT(6.,6.,-999)

C***
C*** PLOT CHANNEL 2
C***
AXX = 4.0 * N
XFIR = 0.0
XINC = 90.0
AYY = 5.0
YFIR = -5000.0
YINC = 2000.0
APOS(N+1) = 0.0
APOS(N+2) = 90.0
CH2(N+1) = -5000.0
CH2(N+2) = 2000.0
ITYPE = 0
ITEXT = 11
CALL PLOTS(0,0,50)
CALL PLOT(1.,1.,-3)
CALL VPISYM(0.75,6.0,0.12,'CHANNEL 2',0.,9)
CALL AXIS(0.0,0.0,'POSITION',-8,AXX,0.0,XFIR,XINC)
CALL AXIS(0.0,0.0,'VOLTAGE',7,AYY,90.0,YFIR,YINC)
CALL LINE(APOS,CH2,N,1,ITYPE,ITEXT)
CALL PLOT(6.,6.,-999)

C***
```

Program VOLT PLOT continued

VOLT PLOT

C*** PLOT CHANNEL 3

C***

```

AXX = 4.0 * N
XFIR = 0.0
XINC = 90.0
AYY = 6.0
YFIR = -7000.0
YINC = 2000.0
APOS(N+1) = 0.0
APOS(N+2) = 90.0
CH3(N+1) = -7000.0
CH3(N+2) = 2000.0
ITYPE = 0
ITEXT = 11
CALL PLOTS(0,0,50)
CALL PLOT(1.,1.,-3)
CALL VPISYM(0.75,6.0,0.12,'CHANNEL 3',0.,9)
CALL AXIS(0.0,0.0,'POSITION',-8,AXX,0.0,XFIR,XINC)
CALL AXIS(0.0,0.0,'VOLTAGE',7,AYY,90.0,YFIR,YINC)
CALL LINE(APOS,CH3,N,1,ITYPE,ITEXT)
CALL PLOT(6.,6.,-999)

```

C***

C***

C*** PLOT CHANNEL 4

```

AXX = 4.0 * N
XFIR = 0.0
XINC = 90.0
AYY = 7.0
YFIR = -14000.0
YINC = 2000.0
APOS(N+1) = 0.0
APOS(N+2) = 90.0
CH4(N+1) = -14000.0
CH4(N+2) = 2000.0
ITYPE = 0
ITEXT = 11
CALL PLOTS(0,0,50)
CALL PLOT(1.,1.,-3)
CALL VPISYM(0.75,6.0,0.12,'CHANNEL 4',0.,9)
CALL AXIS(0.0,0.0,'POSITION',-8,AXX,0.0,XFIR,XINC)
CALL AXIS(0.0,0.0,'VOLTAGE',7,AYY,90.0,YFIR,YINC)
CALL LINE(APOS,CH4,N,1,ITYPE,ITEXT)
CALL PLOT(6.,6.,-999)

```

C***

C***

C*** PLOT CHANNEL 5

```

AXX = 4.0 * N
XFIR = 0.0
XINC = 90.0
AYY = 5.0
YFIR = -5000.0
YINC = 2000.0
APOS(N+1) = 0.0
APOS(N+2) = 90.0
CH5(N+1) = -5000.0

```

Program VOLT PLOT continued

VOLT PLOT

```

CH5(N+2) = 2000.0
ITYPE = 0
ITEXT = 11
CALL PLOTS(0,0,50)
CALL PLOT(1.,1.,-3)
CALL VPISYM(0.75,6.0,0.12,'CHANNEL 5',0.,9)
CALL AXIS(0.0,0.0,'POSITION',-8,AXX,0.0,XFIR,XINC)
CALL AXIS(0.0,0.0,'VOLTAGE',7,AYY,90.0,YFIR,YINC)
CALL LINE(APOS,CH5,N,1,ITYPE,ITEXT)
CALL PLOT(6.,6.,-999)

C***
C*** PLOT CHANNEL 6
C***

AXX = 4.0 * N
XFIR = 0.0
XINC = 90.0
AYY = 6.0
YFIR = -18000.0
YINC = 2000.0
APOS(N+1) = 0.0
APOS(N+2) = 90.0
CH6(N+1) = -18000.0
CH6(N+2) = 2000.0
ITYPE = 0
ITEXT = 11
CALL PLOTS(0,0,50)
CALL PLOT(1.,1.,-3)
CALL VPISYM(0.75,6.0,0.12,'CHANNEL 6',0.,9)
CALL AXIS(0.0,0.0,'POSITION',-8,AXX,0.0,XFIR,XINC)
CALL AXIS(0.0,0.0,'VOLTAGE',7,AYY,90.0,YFIR,YINC)
CALL LINE(APOS,CH6,N,1,ITYPE,ITEXT)
CALL PLOT(6.,6.,-999)
STOP
END

/*
//GO.FT05F001 DD DSN=A529E5.VPI10.FILE1,
//          DISP=OLD,
//          UNIT=TAPE,
//          LABEL=(1,SL),
//          VOL=(,RETAIN,,,SER=200109)
//

```